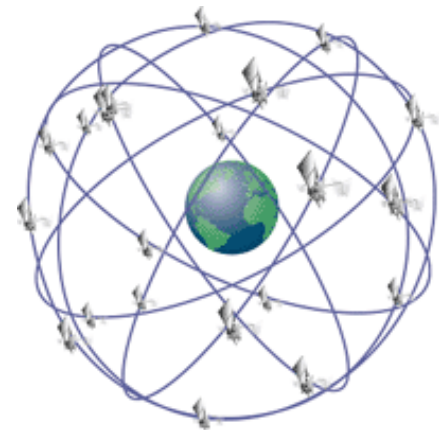


IERS Conventions Implementation Issues

Tim Springer

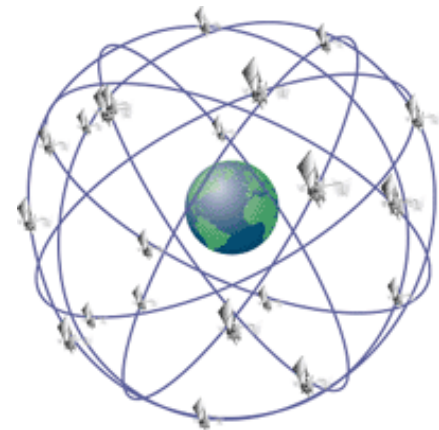
Overview

- Last 2 years at ESOC all IERS 2003 models implemented for GNSS, SLR, and DORIS.
 - New CRF/TRF transformation, Solid tides, Ocean tides, Ocean tidal loading, etc. etc.
 - Sometimes software available sometimes not
 - » Documentation of available software
 - » Quality of available software
- Software comparisons between AIUB, GFZ, and ESOC in the framework of the Galileo Geodetic Service Provider
 - CRF/TRF transformation
 - CMC correction
 - Orbit Integration



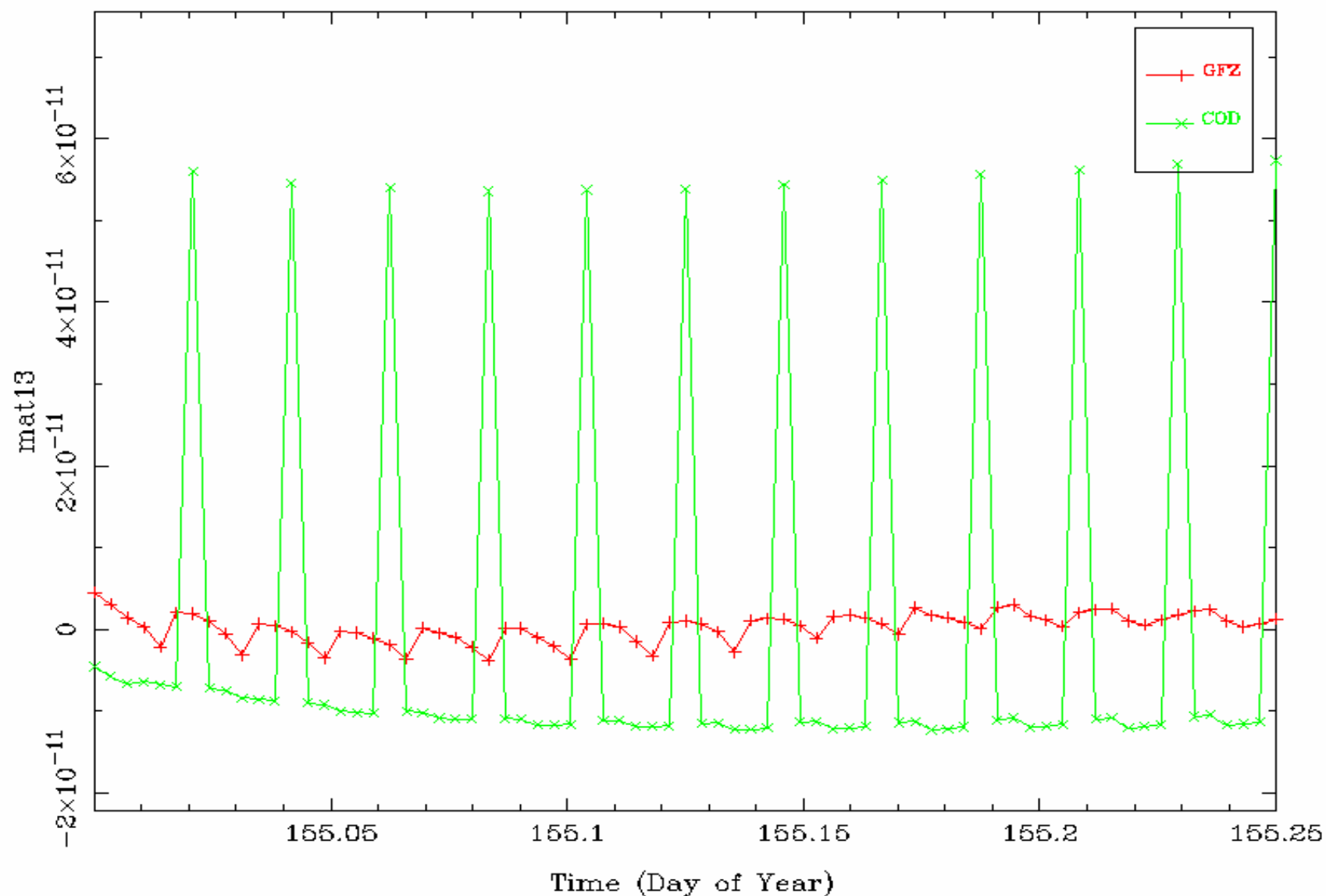
TRF/CRF Transformation

- IERS TRF/CRF software quality is OK.
 - Has documentation
 - Uses “implicit none”
 - Unfortunate that two different notations exist (dpsi/deps vs dX/dY)
 - » At least three different implementation scenarios
 - And....the software is very CPU demanding
 - This causes “special” handling at the ACs
 - » Buffering, interpolation, etc. etc.
 - These implementations have to be tested
 - » Not always easy.



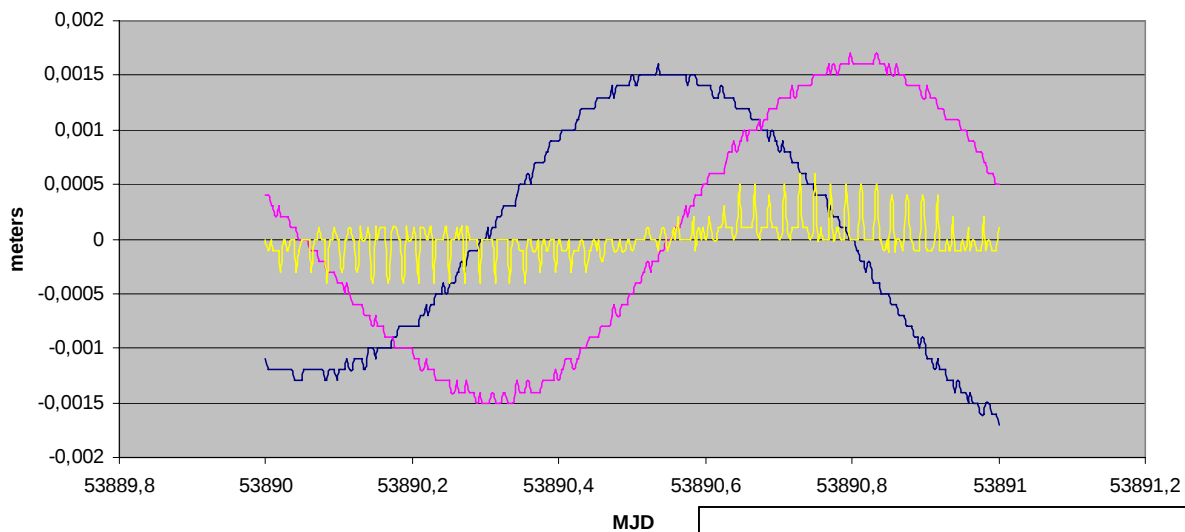
CRF/TRF Interpolation

Zoom of mat13 of GFZ and CODE w.r.t. ESA to look at the spikes

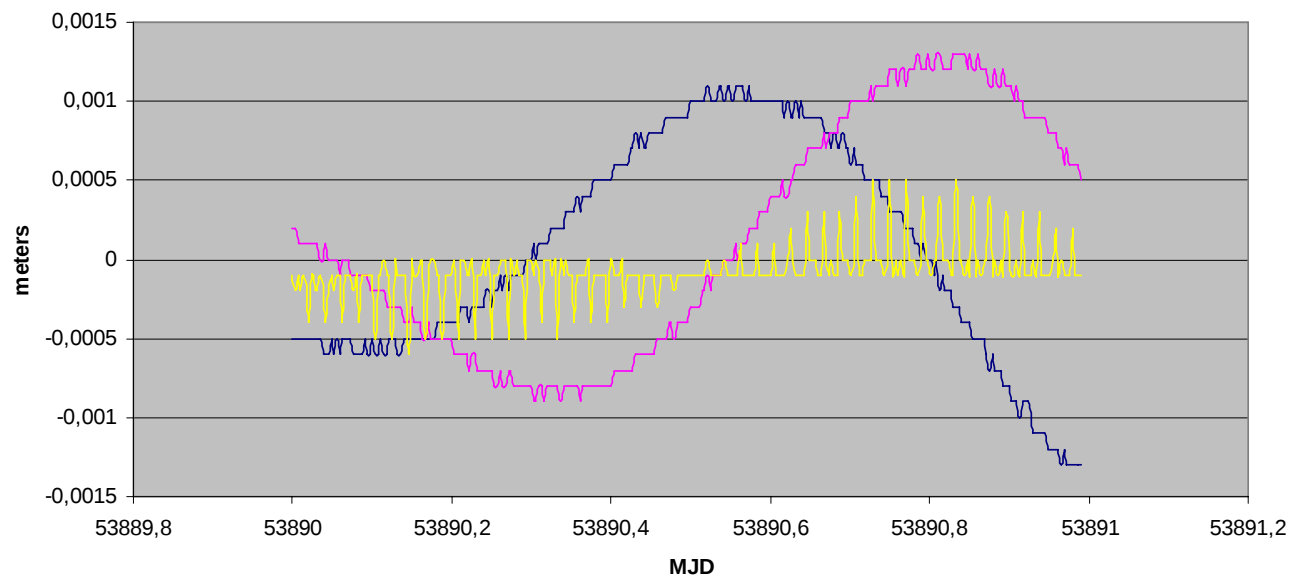


CRF/TRF Interpolation

diff Station X: AIUB - GFZ

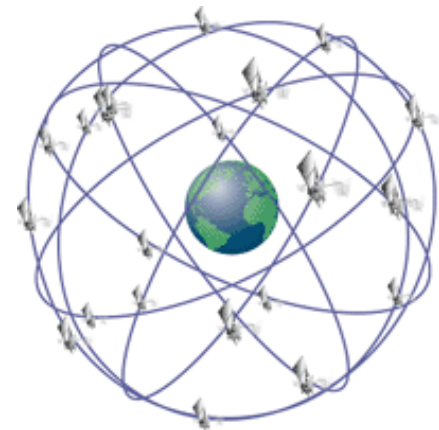


diff Station X: AIUB - ESOC



CMC Correction

- Ocean tidal loading coefficients can be using including or excluding the CMC correction
 - For orbit estimation the CMC correction should be taken into account
 - IGS products are crust based and therefore CMC effect should be “removed” from the orbits
- Ocean tidal loading effects applied using the “hardisp” subroutine
 - This means that also the CMC correction should be applied using the hardisp subroutine.
 - All three ACs used the “classical” (11 constituents) computation to compute the effect of the CMC correction.
 - » Causing discrepancy between computing ocean tidal loading based on coefficient including the CMC effect and coefficients not including the CMC effect but adding the CMC effect separately.
 - » The differences were of equal size as the CMC correction itself!
- Furthermore “hardisp” software has/had several problems
 - Sign error
 - Variable “initial” mistyped as “intial”
 - Long periodic terms still questioned.



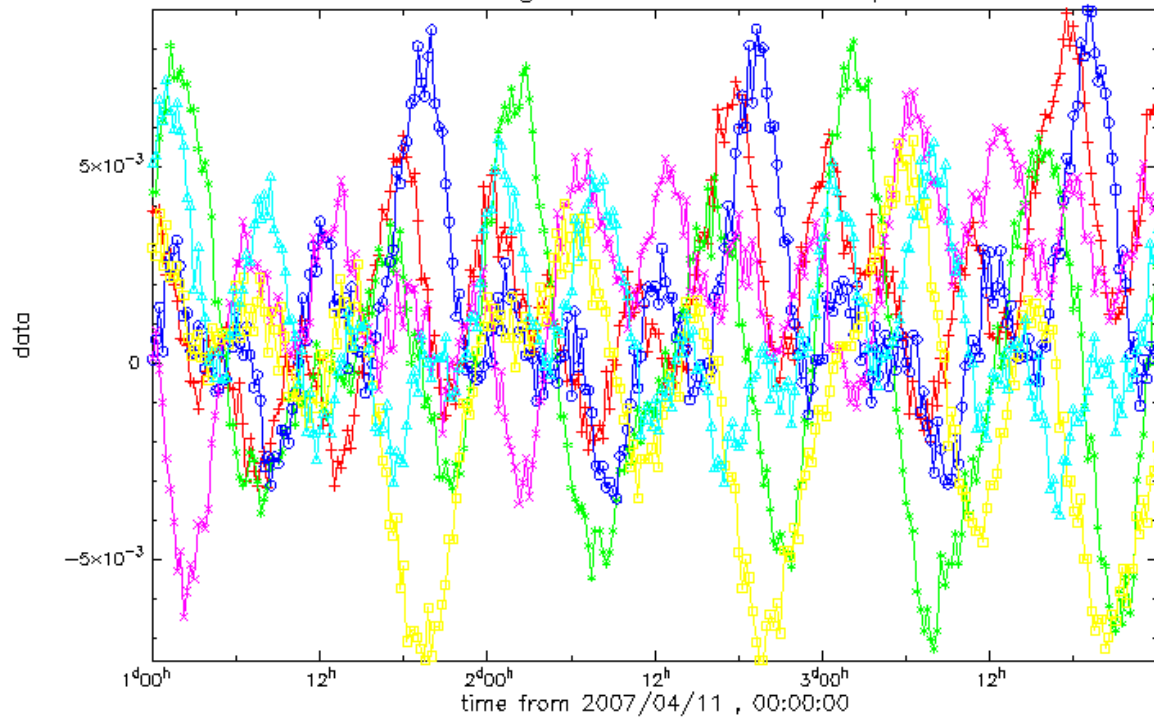
Initial Orbit Integration Differences (ECF)

	RMS orbit differences over 3-days (mm)			
	Radial	Along	Cross	Total
PRN 01 (eclipse)				
AIUB - ESOC	19	285	32	287
AIUB - GFZ	44	123	57	143
ESOC - GFZ	30	242	51	249
PRN 02				
AIUB - ESOC	6	37	44	58
AIUB - GFZ	17	216	57	273
ESOC - GFZ	16	244	59	251

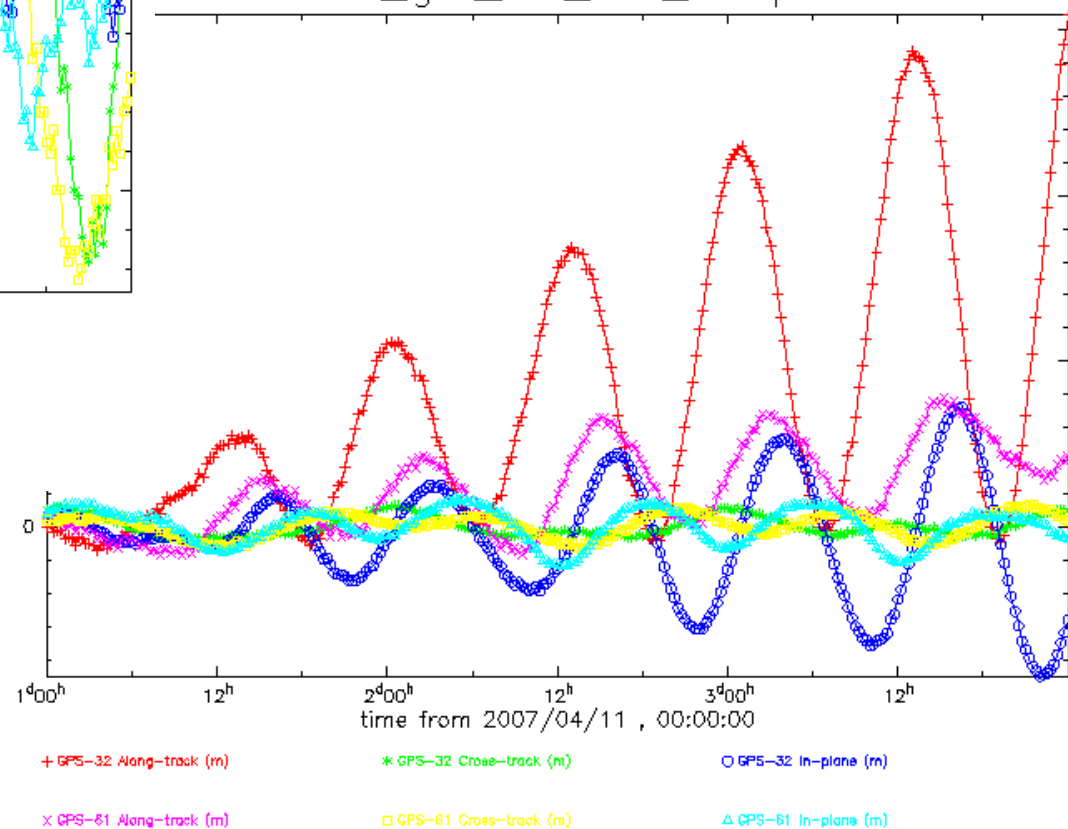
Current Orbit Integration Differences (ECI)

	PRN01 RMS orbit (mm)				PRN02 RMS orbit (mm)			
	Radial	Along	Cross	Total	Radial	Along	Cross	Total
ECI WOT								
AIUB - ESOC	19	88	8	91	6	66	6	66
AIUB - GFZ	45	149	22	157	17	242	34	245
ESOC - GFZ	28	100	19	106	18	303	31	305
ECI NOT								
AIUB - ESOC	18	56	7	59	6	13	8	16
AIUB - GFZ	18	56	5	59	5	12	6	15
ESOC - GFZ	3	2	4	6	3	2	3	5
ECI NOT NST								
AIUB - ESOC	18	56	4	59	5	16	6	18
AIUB - GFZ	18	57	3	60	5	17	3	18
ESOC - GFZ	3	3	4	6	3	3	3	5

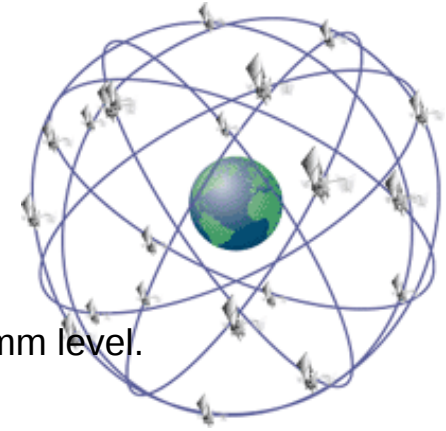
esoc_gfz_eci_not_nst.plt



aiub_gfz_eci_not_nst.plt



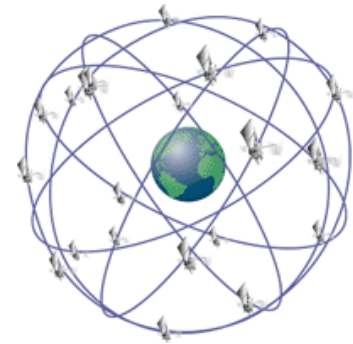
Orbit Integration



- Results still at the hundreds of millimetres!
 - Much worse than expected; GPS uses a simple model
 - Main problems with Ocean Tides; Without Ocean Tides problems are at the 60 mm level.
- Identified problems
 - ESOC Solid Tides implementation (corrected)
 - ECI-ECF transformation problem between ESOC and GFZ.
 - » Z-rotation of 0.25 mas.
 - AIUB ECI-ECF transformation seems to have UT1-UT1R correction disabled.
 - Ocean Tides model of GFZ outdated
 - Ocean Tides implementations at AIUB and ESOC also significantly different.
 - » Most likely caused by usage of different “cut-offs” regarding the used constituents.
Should be investigated.
- Unidentified problem
 - AIUB 60 mm difference compared to GFZ and ESOC for PRN01, even with Ocean and Solid tides turned off.
 - » Relativistic effects, Eclipse “tricks”?

Discussion Points (1/2)

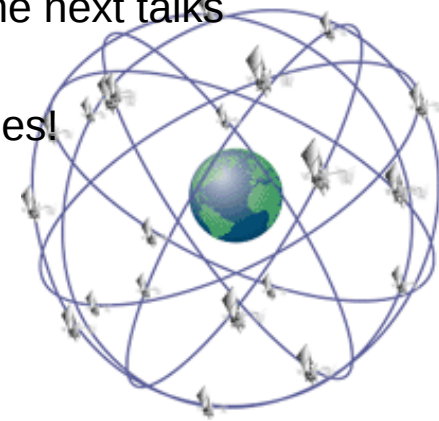
- IERS conventions “internal consistency”
 - FES2004 Ocean Tidal loading but no FES2004 ocean tides for gravity field effect (at least not publicly available)
 - » Should a model be accepted if it is only “partial”, e.g., new ocean tides for station movement but not for gravity.
- IERS conventions software
 - Needs some minimal standards
 - » Use of “IMPLICIT NONE”
 - » A “readme” describing clearly the input and outputs
 - Some routines say MJD as input time. MJD is a time format not a time system!
 - » Some routines do not work beyond 2006 but print a warning.....which may fill your disk!
 - Solid tides subroutine. Also wrong by one month for leap seconds
 - Software should be valid for the next 5 years. If not this should be clearly documented and not just a “warning” message.
 - Each software should come with a set of “reference” results
 - » So that ACs can verify/validate their implementation
 - » So that other experts can study if the selected/provided software is correct



Who and how to handle this within the IERS

Discussion Points (2/2)

- Current level of agreement between IGS ACs is quite poor! Even between two very good ones!!
- We need software tests and validation between the different ACs
 - Seems that ILRS already does this (very good, interested in hearing the next talks on this)
 - Need this for all services (IDS, IGS, and IVS) but also across techniques!
 - » E.g. for troposphere, LEO orbit modelling, etc. etc.!
 - CPU intensive routines are treated in different ways by different ACs
 - » Same CRF/TRF routines give very different answers!
 - » These differences have to be understood, verified, and validated.
 - E.g. “Cut-off” level for ocean tides effect on gravity
- Handle IERS conventions “ambiguity”
 - Often there is more than one convention for a certain model (elastic vs unelastic)



Can and should be handled with the techniques (IDS, IGS, ILRS, IVS)!
How to handle across techniques?